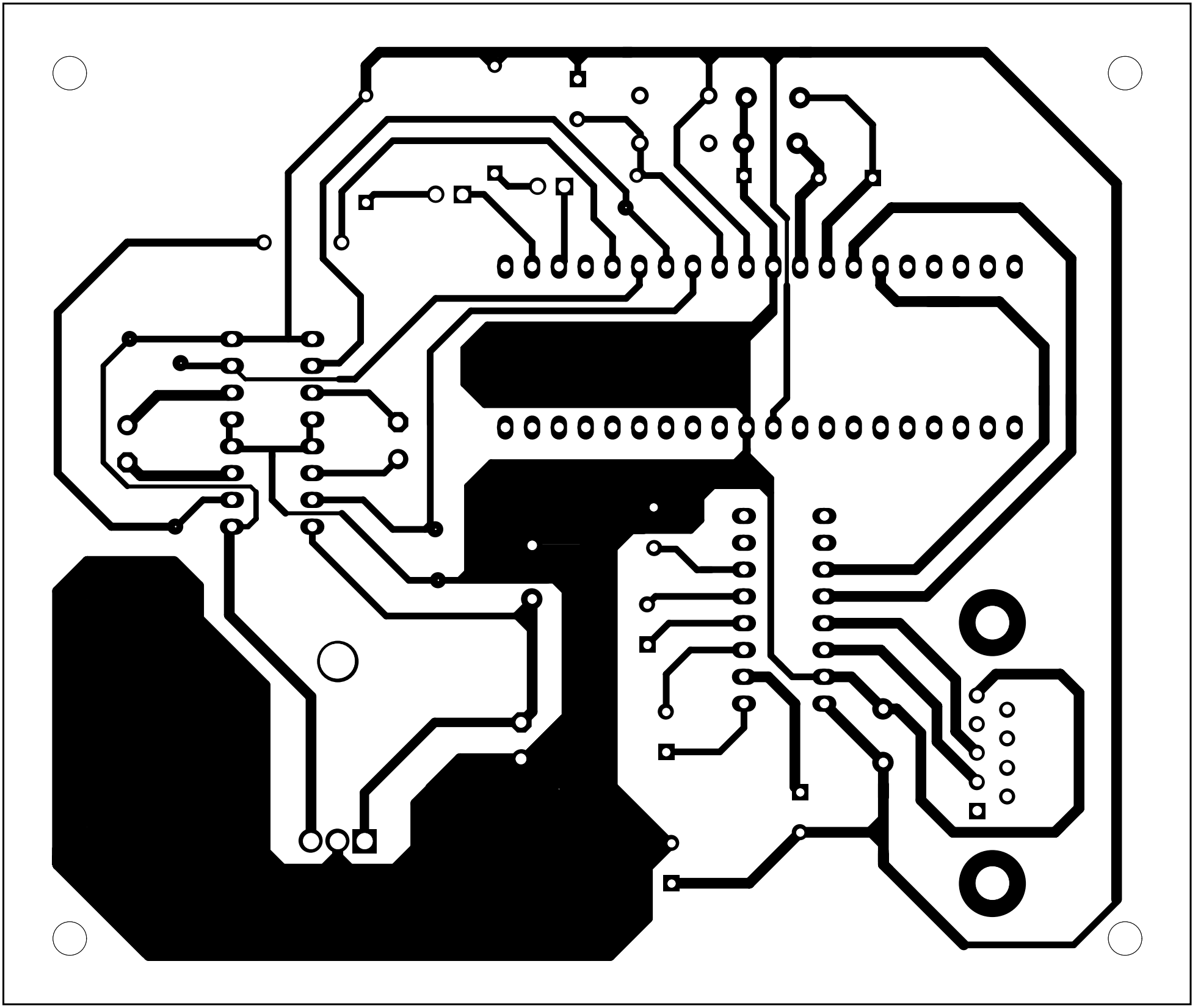

Fig. 7: An actual-size, single-side PCB for the robot